

**Benha University**  
**Faculty Of Engineering at Shoubra**



**ECE 122**  
**Electrical Circuits (2)(2017/2018)**  
**Lecture (10)**  
**Transient Analysis (P3)**

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# Reference Chapter 16

Schaum's Outline Of Theory And Problems Of Electric Circuits  
<https://archive.org/details/TheoryAndProblemsOfElectricCircuits>

## Second-Order RLC Transient (Step Response)

- The Switch "S" is closed at  $t=0$
- Applying KVL will produce the following Integro-Differential equation:

$$Ri + L \frac{di}{dt} + \frac{1}{C} \int i dt = V$$

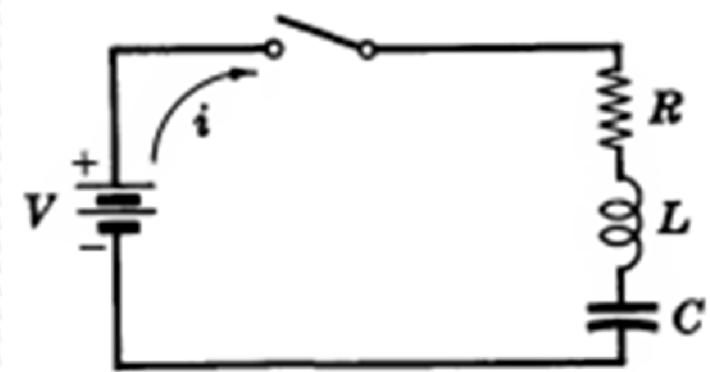
- Differentiating, we obtain

$$L \frac{d^2i}{dt^2} + R \frac{di}{dt} + \frac{i}{C} = 0 \quad \text{or} \quad \left( D^2 + \frac{R}{L}D + \frac{1}{LC} \right) i = 0$$

This **second order**, linear differential equation is of the **homogeneous** type with a **particular solution of zero**.

- ✓ The complementary function can be one of **three different types** according to **the roots of the auxiliary equation** which depends upon the relative magnitudes of R, L and C.

$$m^2 + \frac{R}{L}m + \frac{1}{LC} = 0$$





## Second-Order RLC Transient (Step Response)

We can Rewrite the auxiliary equation as:

$$m^2 + \frac{R}{L}m + \frac{1}{LC} = 0$$

➤ The roots of the equation (or natural frequencies):

$$\begin{cases} m_1 = -\frac{R}{2L} + \sqrt{\frac{R^2}{4L^2} - \frac{1}{LC}} \\ m_2 = -\frac{R}{2L} - \sqrt{\frac{R^2}{4L^2} - \frac{1}{LC}} \end{cases}$$

## Second-Order RLC Transient (Step Response)

### Case 1: Overdamped,

$$\frac{R}{2L} > \frac{1}{\sqrt{LC}} \quad \Rightarrow m_1, m_2 \text{ are real and unequal}$$

Natural response is the sum of two decaying exponentials:

$$i_{tr} = K_1 e^{m_1 t} + K_2 e^{m_2 t}$$

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### Case 2: Critically damped,

$$\frac{R}{2L} = \frac{1}{\sqrt{LC}} \quad \Rightarrow m_1, m_2 \text{ are real and equal.}$$

$$m_1 = m_2 = -\omega_0$$

$$x_c(t) = e^{m_1 t} (B_1 + B_2 t)$$

Use the initial conditions  
to get the constants

Usually it is reduced to:

$$x_c(t) = B.t.e^{m_1 t}$$

## Second-Order RLC Transient (Step Response)

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### Case 3: Underdamped,

$$\frac{R}{2L} < \frac{1}{\sqrt{LC}}$$

$$\sigma^2 < \omega_o^2 \quad \Rightarrow \quad m_1, m_2 \text{ are complex and conjugate.}$$

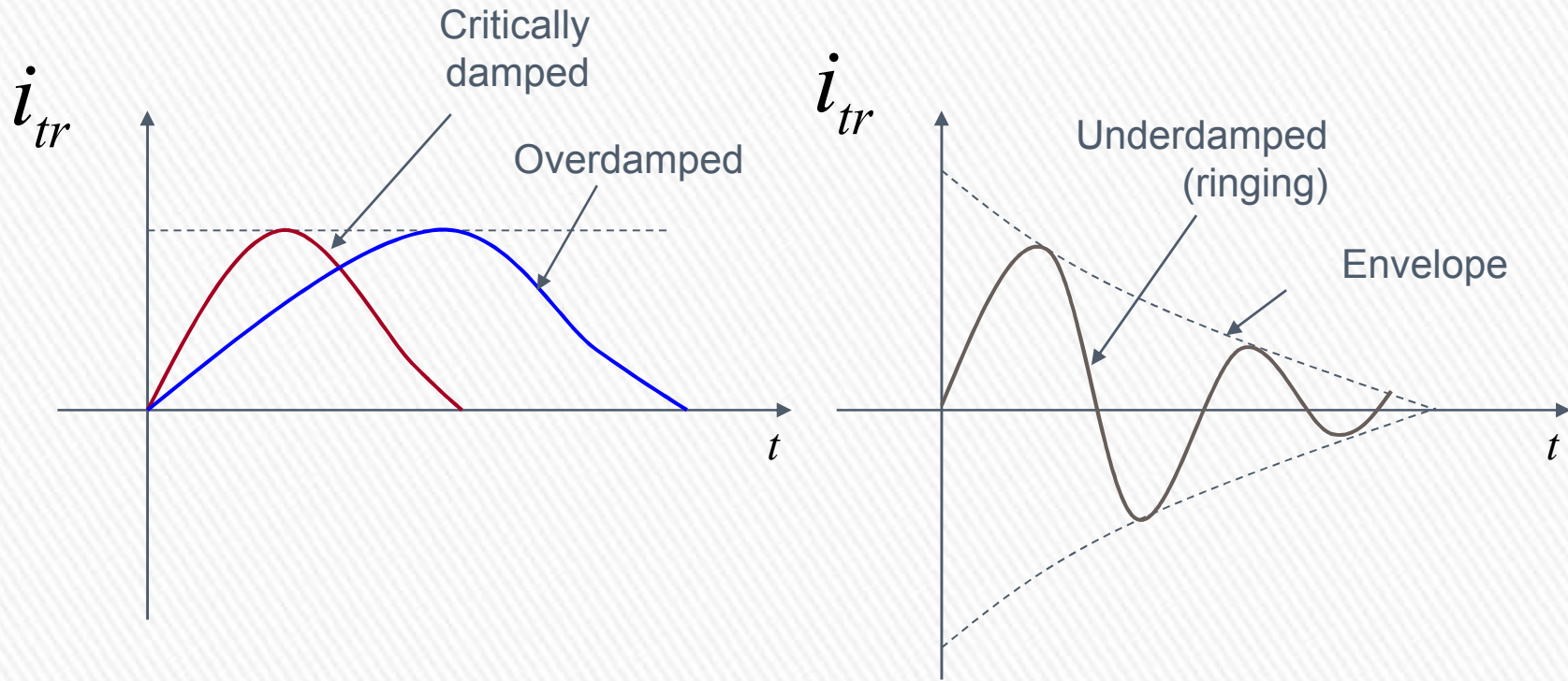
$$\sigma = \frac{R}{2L}$$

Natural response is an exponentially damped oscillatory response:

$$i_{tr} = e^{-\sigma t} \{A_1 \cos(\omega_d t) + A_2 \sin(\omega_d t)\}$$

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- ✓ The current in all cases contains the exponential decaying factor (damping factor) assuring that the final value is zero
- ✓ In other words, assuring that the complementary function decays in a relatively short time.

Example



# Example

A series RLC circuit with  $R = 3000$  ohms,  $L = 10$  h and  $C = 200 \mu\text{f}$  has a constant voltage  $V = 50$  volts applied at  $t = 0$ . Find the current transient and the maximum value of the current if the capacitor has no initial charge.

Handwritten solution for the RLC circuit problem:

$$50 = Ri + L \frac{di}{dt} + \frac{1}{C} \int i dt$$

Substituting values:

$$50 = 3000i + 10 \frac{di}{dt} + \frac{1}{200 \times 10^{-6}} \int i dt \quad \text{①}$$

or  $(D^2 + 300D + 5000)i = 0$

Roots:  $D_1 = -298.3$ ,  $D_2 = -1.67$

General solution:

$$i = C_1 e^{-1.67t} + C_2 e^{-298.3t} \quad \text{②}$$

to find  $C_1, C_2$

at  $t = 0, 0^+ \rightarrow i = 0$  Sub in 1, 2

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$$D = \frac{-B \pm \sqrt{B^2 - 4Ac}}{2A} = \alpha \pm \beta$$

Note  $(\frac{R}{2L})^2 > \frac{1}{LC}$

# Example

∴  $0 = c_1 + c_2 \rightarrow (3)$   
 and at  $t=0 \rightarrow s_0 = 10 \text{ di/dt}$  or  $\text{di/dt} = 5 \rightarrow (4)$

At  $t=0$  ∴  $\text{di/dt} = 5$  ∴  $5 = (-1.67)c_1 - (298.3)c_2$   
 $5 = -1.67c_1 - 298.3c_2 \rightarrow (6)$

∴  $c_1 = 0.168$  and  $c_2 = -0.0168$   
 ∴  $i = 0.0168 e^{-1.67t} - 0.0168 e^{-298.3t}$

to find max current ∴ at  $\frac{di}{dt} = 0$   
 or  $(0.0168)(-1.67) e^{-1.67t} - (0.0168)(-298.3) e^{-298.3t} = 0$   
 $\rightarrow t = 0.0175 \text{ sec}$



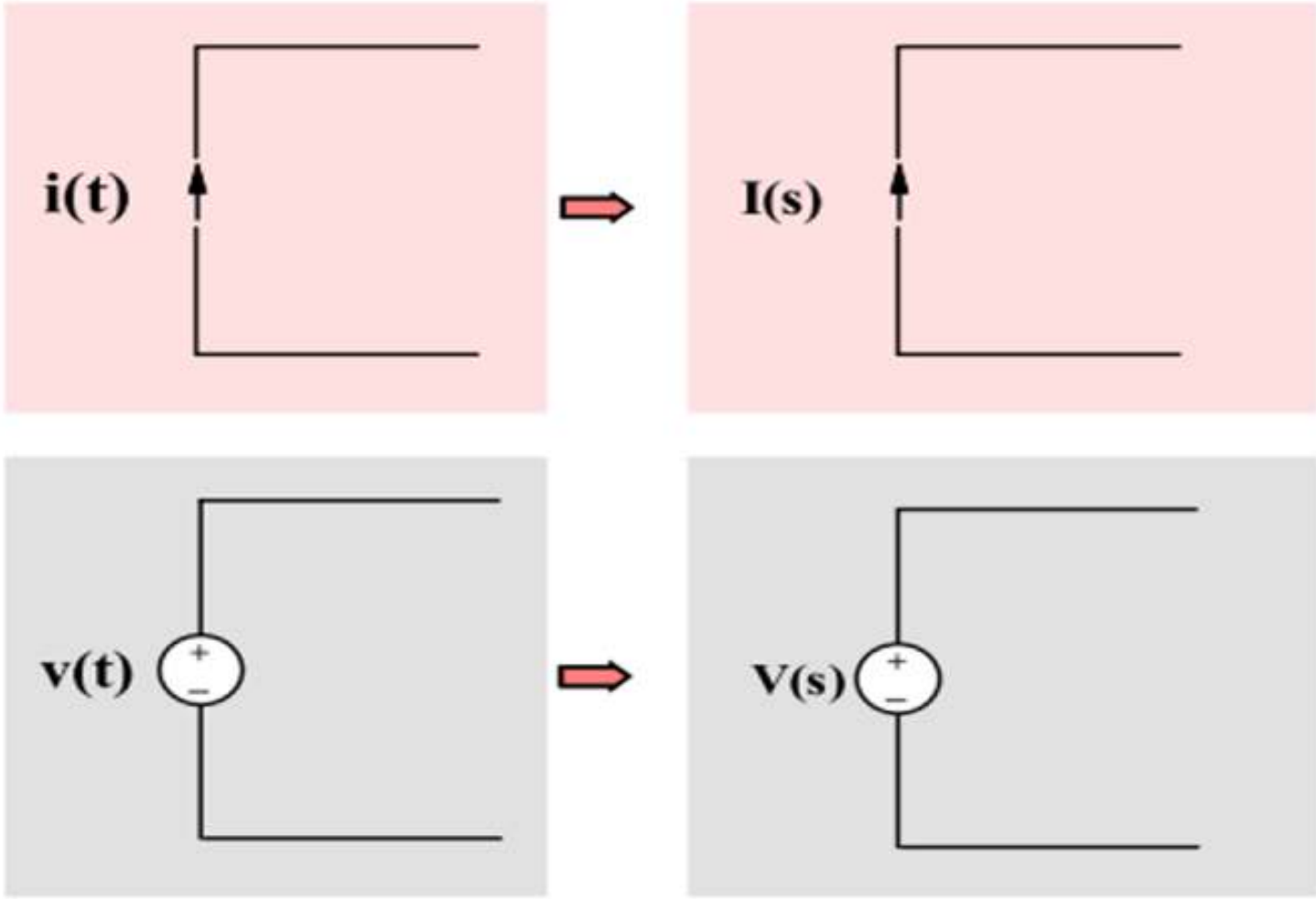
## Transient Analysis using Laplace Transform

- Laplace transform is considered one of the most important tools in Electrical Engineering
- It can be used for:
  - ✓ Solving differential equations
  - ✓ Circuit analysis (Transient and general circuit analysis)
  - ✓ Digital Signal processing in Communications and
  - ✓ Digital Control



# Transient Analysis using Laplace Transform

## Circuit Elements in the "S" Domain



# Circuit Elements in the “S” Domain

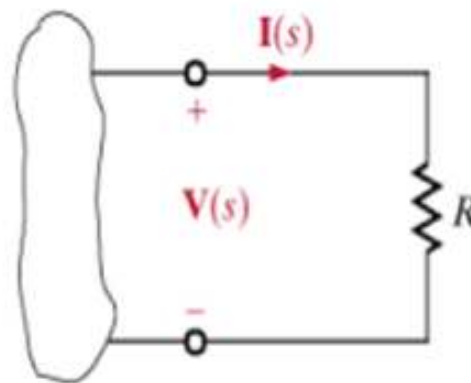
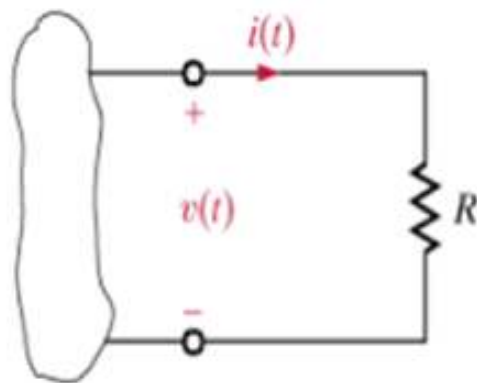
## Circuit Element Modeling

The method used so far follows the steps:

1. Write the differential equation model
2. Use Laplace transform to convert the model to an algebraic form

### 1.0 Resistance

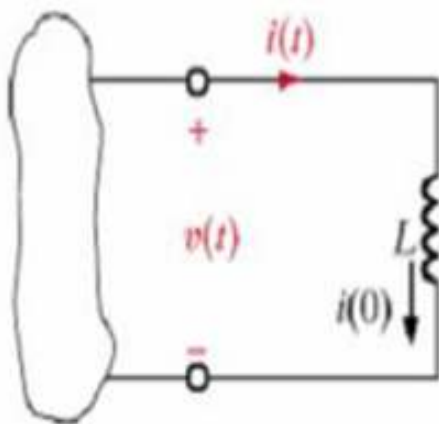
Resistor



$$v(t) = Ri(t) \Rightarrow V(s) = RI(s)$$

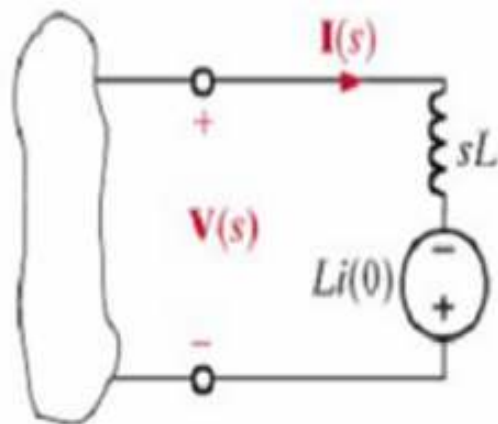
# Circuit Elements in the "S" Domain

## 2.0 Inductor



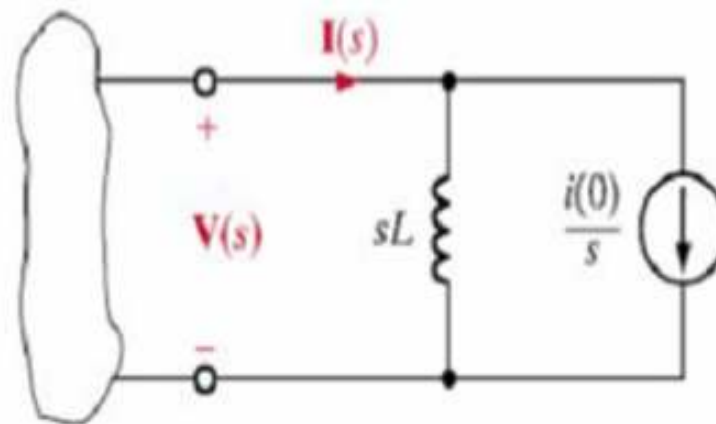
$$v(t) = L \frac{di}{dt}(t)$$

$\Rightarrow$



$$V(s) = LsI(s) - Li(0)$$

$\Rightarrow$

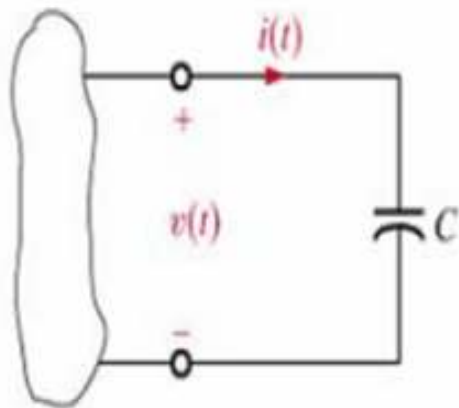


$$I(s) = \frac{V(s)}{Ls} + \frac{i(0)}{s}$$

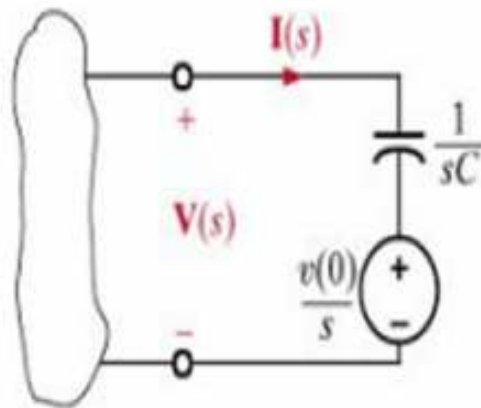


## Circuit Elements in the “S” Domain

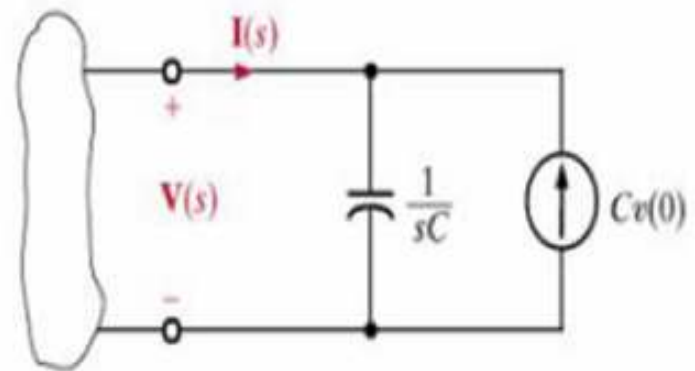
### 3.0 Capacitor



$$v_c(t) = \frac{1}{C} \int_0^t i(t) dt + v_c(0)$$



$$V(s) = \frac{1}{Cs} I(s) + \frac{v(0)}{s}$$



$$I(s) = CsV(s) - Cv(0)$$

## First-Order RC Transient (Step-Response)

- Assume the switch S is closed at  $t = 0$
- Apply KVL to the series RC circuit shown:

$$\left[ \frac{1}{C} \int i(t) \cdot dt + v_c(0) \right] + R \cdot i(t) = V$$

- Apply Laplace Transform on both sides

$$\left[ \frac{I(s)}{Cs} + \frac{v_c(0)}{s} \right] + R \cdot I(s) = \frac{V}{s}$$

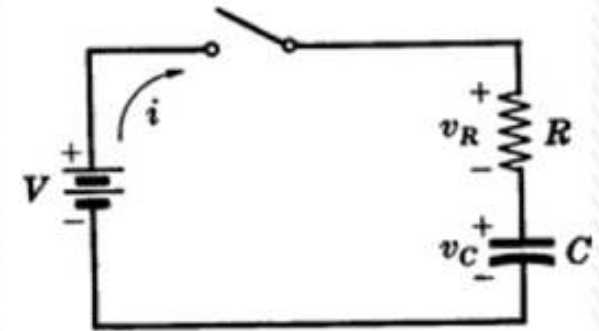
$V_c(0) = 0$  >> initial value of the voltage at  $t = 0$

$$I(s) \cdot \left[ R + \frac{1}{Cs} \right] = \frac{V}{s}$$

$$I(s) = \frac{V/s}{\left[ R + \frac{1}{Cs} \right]} = \frac{V/R}{\left[ s + \frac{1}{cR} \right]}$$

- Apply the inverse Laplace Transform technique to get the expression of the current  $i(t)$

$$i(t) = \frac{V}{R} e^{-\frac{1}{RC}t}; t > 0$$



The same as last lecture

## First-Order RL Transient (Step-Response)

- The switch “S” is closed at  $t = 0$  to allow the step voltage to excite the circuit
- Apply KVL to the circuit in figure:

$$Ri + L \frac{di}{dt} = V$$

Apply Laplace Transform on both sides ➤

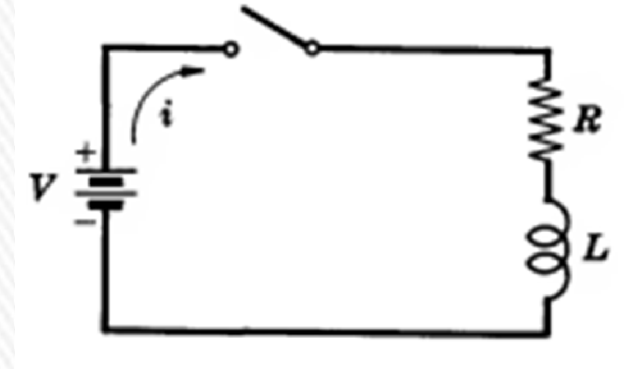
$$R.I(s) + L[s.I(s) - i(0)] = \frac{V}{s}$$

$i(0) = 0$  >> initial value of the current at  $t = 0$

$$I(s).[R + sL] = \frac{V}{s}$$

$$I(s) = \frac{V}{s[R + sL]} = \frac{V/L}{s[s + R/L]}$$

- Apply the inverse Laplace Transform technique to get the expression of the current  $i(t)$





## First-Order RL Transient (Step-Response)

➤ Use the partial fraction technique

$$I(s) = \frac{V/L}{s[s + R/L]} = \frac{A_1}{s} + \frac{A_2}{s + R/L}$$

➤ Multiply both sides by  $s \cdot (s + R/L)$

$$V/L = A_1 \cdot (s + R/L) + A_2 \cdot s$$

$$\dots = (A_1 + A_2) \cdot s + A_1 \cdot \frac{R}{L}$$

$$A_1 = V/R \quad A_2 = -V/R$$

➤ So, the current in s-domain is given by:

➤ Apply the inverse Laplace transform :

The same as last lecture

OR

$$A_1 = \{s * I(s)\} |_{s=0} = \frac{V}{R}$$

$$A_2 = \{(s + R/L) * I(s)\} |_{s=-R/L} = -\frac{V}{R}$$

both sides Compare the coefficients

$$I(s) = \frac{V}{R} \left( \frac{1}{s} - \frac{1}{s + R/L} \right)$$

$$i(t) = \frac{V}{R} \left( 1 - e^{-\frac{R}{L}t} \right); t > 0$$

**Thank You**

